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December 3, 2018

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Abstract

The paper describes a practical, commercial-strength software tool for the verification of integer arithmetic circuits. It covers different types of multipliers, fused add-multiply circuits, and some dividers - the circuits whose computation can be represented as a polynomial. The verification uses an algebraic model of the circuit and is accomplished by rewriting the polynomial of the binary encoding of the primary outputs (output signature), using the polynomial models of the logic gates, into a polynomial over the primary inputs (input signature). The resulting polynomial provides the arithmetic function of the circuit and hence can be used to extract the functional specification from its gate-level implementation. The rewriting uses an efficient *And-Inverter Graph* (AIG) representation to enable extraction of the essential arithmetic components of the circuit. The tool is integrated with the popular ABC system. Its efficiency is illustrated with impressive results for integer multipliers, fuse-multiply circuits, and divide by constant circuits. The entire verification system is offered in an open source ABC environment together with an extensive set of benchmarks.

1 Introduction

Verification of arithmetic circuits can be viewed as a special case of *combinational equivalence checking* [12] in which the function implemented by the circuit is checked against its functional specification. Boolean methods, such as various canonical decision diagrams and SAT, that have been used extensively in logic synthesis and optimization, are computationally too expensive for arithmetic functions as they require “bit blasting”, i.e., flattening the design to a bit-level netlist. The SAT and SMT competition results confirm that the verification of even small multipliers pose a real challenge to such solvers [10]. Similarly, the commercial tools cannot fully automatically handle full-size multipliers [12]. In general, the complexity of checking equivalence of large arithmetic circuits is too high for these methods [9][14].

The techniques that offer best solution for analyzing and verifying arithmetic circuits are formal methods based on *computer algebra* [14][6][8][12]. In this approach, the circuit specification and its implementation are represented as polynomials in binary signal variables. The verification problem is formulated as a proof that the implementation satisfies the specification. It is accomplished by reducing the specification modulo the implementation polynomials using theory of *Gröbner Basis*, which transform the verification problem into *membership testing* of the specification polynomial in the ideals [8][6][12][10]. Some of the authors [6][4] use Gaussian elimination, rather than explicit polynomial division, to speed up the reduction process.

An alternative, and more effective approach to accomplish the verification proof for gate-level arithmetic circuits is based on *algebraic rewriting* [14][15]. It transforms the polynomial at the primary outputs (called the *output signature*) to a polynomial in terms of primary inputs (the *input signature*) [14]. The resulting signature provides the functional specification of the circuit that can be compared with the expected specification, hence the method can also serve as *function extraction*. Although this approach has been successfully applied to

large-scale multipliers and other arithmetic circuits, it still suffers from a potential memory explosion problem during rewriting due to the growing size of the intermediate polynomials. In particular, the method is very sensitive to the order in which rewriting is done, strongly affecting the verification performance.

The verification method and the tool presented in this paper offer an important step in finding an efficient solution to the arithmetic verification problem. The method is based on representing the circuit in a *functional*, rather than structural, gate-level domain, called the *And-Inverter Graph* (AIG) [7], in which the algebraic rewriting is done on the AIG representation of the circuit.

2 Algebraic Rewriting

Arithmetic circuit considered in this work is a circuit that computes polynomial expressed in the input variables. The circuit is modeled as a network of interconnected bit-level components (logic gates), each with a finite set of binary inputs and a single binary output. Each gate is modeled as a polynomial $f_i[X]$ with binary variables $X = \{x_1, \dots, x_n\}$ and coefficients in \mathbb{Z}_2 . Such a polynomial is also referred to as a *pseudo-Boolean polynomial*. Table 1 summarizes algebraic models of some of the basic Boolean operators:

Table 1: Boolean and algebraic models of basic logic functions.

Operation	Boolean model	Algebraic model
$INV(a)$	$\neg a$	$1 - a$
$AND(a,b)$	$a \wedge b$	ab
$OR(a,b)$	$a \vee b$	$a + b - ab$
$XOR(a,b)$	$a \oplus b$	$a + b - 2ab$
$XOR3(a,b,c)$	$a \oplus b \oplus c$	$a + b + c - 2ab - 2ac - 2bc + 4abc$
$MAJ3(a,b,c)$	$a \wedge (b \vee c) \vee b \wedge c$	$ab + ac + bc - 2abc$

By construction, each expression evaluates to a binary value (0,1) and correctly models the logic function of a Boolean logic gate. Models for more complex AOI (And-Or-Invert) gates, used in standard cell technology, are readily obtained from these basic logic expressions. For example, algebraic model for logic gate $g = a \vee (b \wedge c)$ can be derived as $g = a + bc - abc$, etc.

Algebraic rewriting relies on relating two pseudo-Boolean polynomials, called an output signature and an input signature. The *output signature*, Sig_{out} , is the polynomial that represents the result stored as the binary encoding of the primary outputs. For example, an output signature of a signed 2's complement arithmetic circuit with n bits, $Sig_{out} = -2^{n-1}z_{n-1} + \sum_{i=0}^{n-2} 2^i z_i$. By construction, such a polynomial is unique. The *input signature*, Sig_{in} , is the polynomial over the primary input variables that represents the arithmetic function performed by the circuit, i.e., its *functional specification*. For example, for an n -bit binary adder with inputs $\{a_0, \dots, a_{n-1}, b_0, \dots, b_{n-1}\}$, it is $Sig_{in} = \sum_{i=0}^{n-1} 2^i a_i + \sum_{i=0}^{n-1} 2^i b_i$. In our approach, the input specification need not be known; it will be derived from the circuit implementation by algebraic rewriting.

Algebraic rewriting is the process of transforming Sig_{out} into Sig_{in} using algebraic models of the internal components (logic gates) of the circuit, such as those specified by Table 1. By definition, it is done in the reverse topological order: from the primary outputs (PO) to the primary inputs (PI); for this reason it is also referred to as a *backward rewriting* [14]. Intermediate expression obtained during rewriting is also represented as a polynomial, referred to as a *signature*, over the variables representing the internal signals of the circuit. By construction, each variable in a given signature polynomial (starting with Sig_{out}) represents an output of

some logic gate. The rewriting transformation simply replaces that variable with the algebraic expression of the corresponding logic gate.

It has been shown that such a backward rewriting is unique [14]. However, its performance strongly depends on the order in which the individual variables are rewritten. Two basic rules are used in determining the rewriting order: (1) Rewriting follows reverse topological order; and (2) Signals that depend common signals (fanins) are rewritten together (i.e., one immediately after the other). The first rule is obvious because of the direction in which the signature is propagated. As a result, the final signature will be expressed in the PI inputs only. The second rule is dictated by the fact that rewriting together the nodes with common fanins maximizes the chance for potential term cancellation.

To illustrate the rewriting process consider the following example of a gate-level arithmetic circuit with inputs a, b, c_0 , shown in Figure 1(a). The output signature of the circuit is $Sig_{in} = 2C + S$, determined by the weights of the two output signals dictated by the binary encoding. The goal is to determine the arithmetic function implemented by this circuit (or, equivalently to verify if it is a full adder) by rewriting Sig_{out} into an input signature (specification), Sig_{in} .

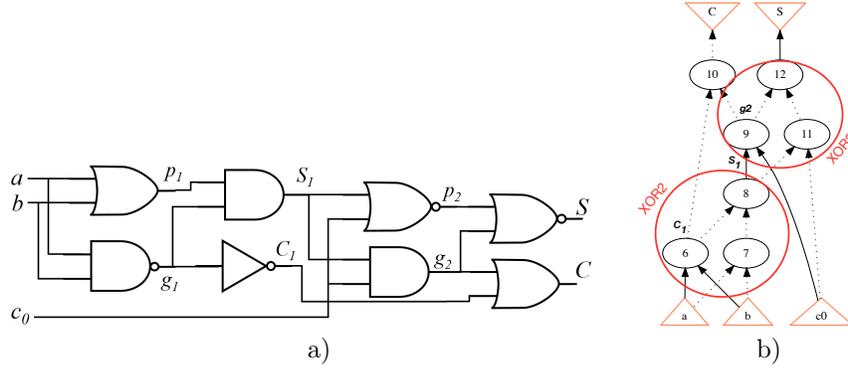


Figure 1: Gate-level arithmetic circuit (FA): a) circuit diagram; b) AIG representation

According to the rewriting algorithm [14] the optimum rewriting order is $\{(S, C), (p_2, g_2), (S_1, C_1), (p_1, g_1)\}$. The signals shown in brackets are the ones that depend on common inputs; they are to be rewritten together, i.e., one immediately after the other. The detailed steps of the algebraic rewriting are shown in the **Appendix**. During the rewriting two types of simplifications can be observed:

- Simplification by adding or subtracting terms with the same monomials. For example in Step 1: $2g_2 - g_2 = g_2$; and
- Simplification by lowering x^k with degree $k > 1$ to x . This is based on the fact that all variables in the circuit are binary, such that $x^k = x$. For example, in Step 3 of the rewriting, shown there in bold face: $(p_1g_1 - p_1g_1^2) = p_1g_1 - p_1g_1 = 0$. Similar simplifications appear in steps 2 and 4.

The resulting input signature is $Sig_{in} = a + b + c_0$, indicating that this is a full adder.

3 AIG Rewriting

In contrast to the algebraic rewriting applied directly to a gate level circuit, as in Figure 1(a), the rewriting employed in our tool operates on the functional AIG representation of the circuit [15]. AIG (And-Inverter Graph) is a combinational Boolean network composed of two-input AND gates and inverters [7]. Each internal node of the AIG represents a two-input AND function;

the graph edges are labeled to indicate a possible inversion of the signal. We use the *cut-enumeration* approach of ABC to detect XOR and Majority (MAJ) functions with a common set of variables. Those nodes are essential in identifying half-adders (HA) and full-adders (FA), the basic components of an arithmetic circuit [15]. AIG rewriting then skips over the large portions of the circuitry, from the inputs to the outputs of the adders, significantly speeding up the rewriting process, as shown in Figure 1(b). The algorithm is outlined in Algorithm 1.

Algorithm 1 Algebraic Rewriting in AIG

Input: Gate-level netlist N ; Output signature Sig_{out}

Output: *Pseudo-Boolean* expression extracted by rewriting

- 1: $G(V, E) \leftarrow$ structural hashing of N into AIG.
 - 2: Detect all XOR3 and MAJ3 nodes in $G(V, E)$.
 - 3: $P \leftarrow$ Pair (XOR3, MAJ3) nodes with common signals.
 - 4: Topological sort $G(V, E)$ considering each element in P as one node.
 - 5: $i = 0$; $F_i = Sig_{out}$
 - 6: **while** there remain elements in V **do**
 - 7: Rewrite: $F_{i+1} \leftarrow F_i$ by variable substitution;
 - 8: $i = i + 1$
 - 9: **end while**
 - 10: **return** $F = F_i$ (to be compared with Sig_{in})
-

The inputs to the algorithm are the gate-level netlist N and the output signature Sig_{out} and includes four basic steps: 1) converting the gate-level implementation into AIG; 2) detecting all pairs of (XOR3, MAJ3) functions with common AIG inputs¹; 3) performing topological sorting of AIG nodes while treating the detected XOR and MAJ functions as a single element; and 4) applying algebraic rewriting from POs to PIs following the reverse topological order. As soon as the matching (XOR3, MAJ3) pairs are detected, a hybrid graph G is constructed, in which each XOR3 and MAJ3 function is considered as a single node. In the absence of XOR3, MAJ3 nodes, the two-input XOR2 and MAJ2(AND) functions are similarly detected. Algebraic rewriting is then applied to the modified graph G in a reverse topological order. The algorithm returns the extracted input signature Sig_{in} .

In the example of Figure 1(b), the groups of nodes (6,7,8) and (9,11,12) are identified as XOR2, and nodes 6 and 9 as the matching MAJ2(AND) functions. Subsequently, the functions at node 12 (S) and node 10 (C) are identified as XOR3 and MAJ3, respectively, sharing the same inputs, a, b, c_0 . At this point the entire graph G reduces to just two nodes, representing XOR3(a, b, c) and MAJ3(a, b, c). The rewriting of $Sig_{out} = 2C + S$ over the two nodes is trivial, with the nonlinear monomials cancelled as follows (refer to Table 1):

$$2C + S = 2(ab + ac_0 + bc_0 - 2abc_0) + (a + b + c_0 - 2ab - 2ac_0 - 2bc_0 + 4abc_0) = a + b + c_0$$

As illustrated with this example, the AIG rewriting requires considerably fewer terms than the standard algebraic rewriting.

4 Results

The algebraic rewriting environment was implemented in C and integrated with the ABC tool [1], where it is available under command *ℰpolyn*. Here we present an **open source** framework of Algebraic Rewriting (ARTi) system for verifying arithmetic circuits using the most recent version of ABC². The results include some challenging nonlinear arithmetic circuits: large multipliers and divide-by-constant circuits. Comparisons are made w.r.t. the state-of-the-art tools

¹XOR2 and MAJ2(AND2) are special cases of XOR3 and MAJ3, with one of the inputs being constant zero.

²<https://github.com/ycunxi/abc>

in this domain, [10][11] and [12], which are all computer algebra based systems. The comparison with SAT, SMT, and commercial systems are not provided here since computer algebraic approach has already been proved to be orders of magnitude faster than those techniques [14]. Other sources also report inadequate quality of these tools for arithmetic verification [12][10].

4.1 Multipliers

The experiments were conducted on benchmarks released in [10][11]³. For fair comparison, we recompiled their C code on our platform and evaluated it with the state-of-the-art computer algebra system, Singular v4.1.1 [3]. The experiments were conducted on a PC with Intel(R) Xeon CPU E5-2420 2.20 GHz x24 with 1 TB memory. The memory out (MO) limit is 100 GB and timeout (TO) limit is 3600 seconds. Singular reports error state (ES) if the circuit contains more than 32,767 ring variables (limit imposed by Singular). The verification results for pre-synthesized multipliers are included in Table 2. The results in column ARTi are generated using three sets of commands, for *btor*, *sp-ar-rc*, and *abc* multipliers as follows:

- *read btorXX.aig; &get; &polyn -o -v;* for the *btor-XX* multipliers;
- *read sp-ar-rcXX.aig; &get; &atree; &polyn -o -v;* for the *sp-ar-rc-XX* multipliers;
- *gen -N XXX -m abcXXX.blif; &get; &polyn -o;* for the *abc-XXX* multipliers.

The command *&polyn* includes various algebraic rewriting options, with *-o* flag indicating the use of the older version of the rewriting algorithm [14]. Command *&atree* invokes extraction of adder trees in the circuit.

Table 2: Verification time (sec) for pre-synthesized multipliers. ES = error reported by Singular.

Designs	ARTi	[10]	[11]	Designs	ARTi	[10]	[11]
btor-16	0.01	0.5	0.01	sp-ar-rc16	0.01	1.1	0.01
btor-32	0.02	11.7	0.3	sp-ar-rc32	0.1	35.5	0.3
btor-64	0.1	725	4.0	sp-ar-rc64	0.4	1312	4.6
btor-128	0.5	ES	ES	sp-ar-rc128	1.6	ES	ES
abc-256	1.0	ES	ES	abc-512	4.5	ES	ES

Table 3 shows the results for for multipliers mapped onto standard cells with three different libraries, including *industrial libraries* of 14 nm and 7 nm technology nodes. The results of verifying the same set of benchmarks using the open source tools available from [10][11], are included. The results of the first seven designs in the Table are generated using command-**a** in Table 2. For the last two circuits, mapped onto industrial libraries, we executed several iterations of *dch* and *strash* commands before ARTi to eliminate extra logic introduced for the purpose of meeting the timing constraints.

4.2 Complex Arithmetic Circuits

Table 4 shows the results of extracting word-level specifications from gate-level complex arithmetic circuits, constructed with multiplication and addition operations, and a three-operand multiplier. The multiplications in these datapaths are implemented using ABC-generated multipliers. Our approach can efficiently identify the word-level operations in the gate-level datapaths. In contrast, the approach of [13] could not detect the presence of multiplication or addition in these circuits; and our approach is much faster than [14].

³<http://fmv.jku.at/algeq/>

Table 3: Verification time (sec) of synthesized, technology mapped multipliers using different libraries. #GT = Number of gate types used. FI ≥ 5 = Number of gates with fanin ≥ 5 .

Designs	ARTi	#GT	FI ≥ 5	[10]	[11]
btor64-resyn3	0.1	-	-	711	4.2
abc64-resyn3	0.1	-	-	801	4.0
btor128-resyn3	0.3	-	-	ES	ES
abc128-resyn3	0.1	-	-	ES	ES
btor64-resyn3-map-simple	0.3	7	0	1073	418
abc64-resyn3-map-simple	0.1	7	0	1071	415
abc64-resyn3-map-14nm	35	15	17	TO	TO
abc64-resyn3-map-7nm	MO	24	9,791	TO	TO
abc128-resyn3-map-simple	1.8	7	0	ES	ES
abc128-resyn3-map-14nm	406	15	1,008	ES	ES
abc128-resyn3-map-7nm	MO	23	26,600	ES	ES

Table 4: Results of extracting word-level specification from complex arithmetic circuits. *TO* = TIME OUT (3600 s). *Error* = Unable to determine type of arithmetic operations. *TO**: finished in 23,760 s.

256-bit	[13]	[14]	Ours	
$F=A \times B+C$	Error	TO*	1 \times mult;1 \times add	44.7 s
$F=A \times (B+C)$	Error	TO	2 \times mult	45.1 s
$F=A \times B \times C$	Error	TO	1 \times mult3	68.5 s

4.3 Dividers (Divide by Constant)

This section presents the results for a special class of dividers, namely divide-by-constant circuits. Their function can be expressed as $X = Q \cdot D + R$, where the divisor D is a constant. First, we consider an architecture based on a standard *restoring divider* [5], in which the divisor D has been hardwired to a particular constant. The restoring divider has been implemented and synthesized using ABC, where the constants associated with the bits of D are propagated through the circuit and used to optimize the circuit.

The first step is to create the output signature Sig_{out} , specific for the constant divisor. It is obtained by our program written in python as follows:

```
python verify_constant_divider_abc.py -f div-test-3-3-3-3.blif -divisor 011 -divexp 1+0.
```

In the case of the divide-by-3 (with X, Q, C, R all being 3-bit words), the output signature for the output $Z = [Q_2Q_1Q_0R_2R_1R_0]$, is:

$Sig_{out} = 3(Q_0 + 2Q_1 + 4Q_2) + R_0 + 2R_1 + 4R_2 = (1 + 0) * (0 * Q_0 + 1 * Q_1 + 2 * Q_2) + (0 * R_0 + 1 * R_1 + 2 * R_2)$ This signature is coded in a compact way using only exponents k of coefficients 2^k , resulting in the string shown below after the switch $-S$. The following ABC command is then used to generate Sig_{in} :

```
read final-div-test-3-3-3-3.blif; sweep; strash; dch; &get;
&polyn -v -w -S 3*o0+4*o1+5*o2-1*o0-2*o1-3*o2+0*o3+1*o4+2*o5;
```

The resulting input signature (specification) obtained by ABC is $0 * i0 + 1 * i1 + 2 * i2 = 1 * X_0 + 2 * X_1 + 4 * X_2$, which indicates that the circuit correctly implements the division by 3. Table 5 shows the solutions for different divisors for a 16-bit dividend X .

We also present an alternative, modular divider architecture, in which the divider is partitioned into a number of blocks connected in series, each having a fixed number of bits for the dividend X and quotient Q . A carry-in C into each block comes from the remainder R of the previous block. The number of bits of C and R is fixed and determined by the number of bits of the divisor D . Each basic block for a given divisor D is implemented as a lookup table (LUT). The circuits were generated using an open-source hardware generator, FloPoCo [2], and synthe-

Table 5: Results of verifying the divide-by-constant **restoring divider** circuit for a 16-bit dividend X . Time-out of 20 mins, Memory-out 24GB.

Divisor	# Rem. bits	Time (s) (No bug)	Divisor	# Rem. bits	Time (s) (No bug)
11	4	2.42	157	8	16.5
17	5	4.13	191	8	MO
31	5	10.7	223	8	317
43	6	9.22	241	8	125
53	6	3.83	251	8	2.20
61	6	9.22	257	9	16.9
73	7	5.96	263	9	223
89	7	11.0	277	9	30.7
101	7	2.14	283	9	22.3
131	8	15.1	311	9	326

sized using ABC tool [7] onto standard cell, gate-level circuits. The experiments include both

Table 6: Verification results of divide-by-constant divider circuits for a one-bit block architecture and a 32-bit dividend X . Time-out of 20 minutes.

Divisor	# Rem. bits	# Gates	Time (s) (No bugs)	# Bugs	Time (s) (With bugs)
17	5	1763	0.81	3	0.75
61	6	3715	3.50	8	3.56
113	7	3652	6.68	7	7.21
241	8	4891	21.7	7	30.42
251	8	6410	110.4	5	113.5
263	9	8114	29.3	8	39.1
277	9	8238	T/O	-	-
283	9	8951	643.8	9	638.4

correct (bug-free) and faulty circuits. The faults were emulated by randomly injecting multiple faults in the truth table into the valid portion of the LUT. Table 6 includes the verification time for the divide-by-constant, one-bit (of X) block architecture. The results are shown for a 32-bit dividend X , divisors D value up to 283, and a 9-bit remainder R . The non-monotonic behavior of the verification time as a function of the divisor size can be explained by examining the content (on-set) of the truth table for the corresponding division and its dependence on the value of the divisor.

4.4 Interactive Examples

The following example shows the script and the results of verifying (by deriving the specification of) a 64-bit multiplier using ABC system with `&polyn` command. It can be obtained by the following script:

```
./abc -c "gen -N 64 -mmult -abc -64.blif; strash; print_stats; &get; &ps; &polyn -w" > mult64.log
```

The results (on the right) are shown in two formats: implicitly, by listing the number of coefficients appeared in the computed polynomial; and explicitly by listing all the monomials (only some are listed here for brevity).

```
abc 01> gen -N 64 -m mult64-abc.blif;st;strash;ps
Hierarchy reader flattened 8256 instances of logic boxes and left 0 black boxes.
Multi64          : i/o = 128/ 128 lat = 0 and = 32064 lev =501
abc 04> &get;&ps;
```

```
Multi64 : i/o = 128/ 128 and = 32064 lev = 501 (312.05) mem = 0.37 MB
```

Verbose option 1

```
abc 04> &polyn -w
Polynomial with 4096 monomials:
| +2^0 * i0 * i64
| +2^1 * i0 * i65
  +2^1 * i1 * i64
| +2^2 * i0 * i66
...

```

Verbose option 2

```
abc 04> &polyn -v
Input signature with 4096 monomials:
+2^0 appears 1 times
+2^1 appears 2 times
+2^2 appears 3 times
+2^3 appears 4 times
...

```

The following log shows the usage of the tool by explicitly providing the output signature Sig_{out} in terms of the weights of the output bits. $Sig_{out} = 1z_0 + 2z_1 + 4z_2 + 8z_3$ is coded showing only exponents of the coefficients: $0^*o0+1^*o1+2^*o2+3^*o3$, with symbol o_k referring to the k th output bit with coefficient 2^k .

```
abc 01> gen -N 2 -m mult-abc-2.blif; strash; &get; &polyn -w -S 0*o0+1*o1+2*o2+3*o3
Hierarchy reader flattened 10 instances of logic boxes and left 0 black boxes.
HashC = 7. HashM = 25. Total = 40. Left = 4. Used = 4. Time = 0.00 sec
Input signature with 4 monomials:
+2^0 appears 1 times
+2^1 appears 2 times
+2^2 appears 1 times
Polynomial with 4 monomials:
| +2^0 * i0 * i2
| +2^1 * i0 * i3
  +2^1 * i1 * i2
| +2^2 * i1 * i3

```

The computed input signature is $Sig_{in} = 1i_0i_2 + 2i_0i_3 + 2i_1i_2 + 4i_1i_3$, which clearly indicates the signature (specification) of the 2-bit unsigned multiplier, $(i_0 + 2i_1)(i_2 + 2i_3)$.

An example of gate-level backward rewriting is demonstrated with our tool *petBoss*[14]⁴. This tool takes an equation file (one example included in the source directory) and produces the computed polynomial. The Sig_{out} must be provided at the bottom of the equation file.

```
~/abc/petBoss/petBoss-source: ./petBoss -b < ../mult4-syn.eqn
>>>>>>>>>>>>>>>>a0*b0+2*a0*b1+2*a1*b0+4*a0*b2+...+32*a2*b3+32*a3*b2+64*a3*b3
>>>How'd I do?
```

5 Appendix

Rewriting steps for the gate-level circuit shown in Figure 1(a), using the algebraic models of logic gates in Table 1. The terms shown in bold face are the ones that get reduced to 0 during simplification. For brevity, the substitution is shown for each pair of variables at once. For

⁴<https://github.com/ycunxi/abc/tree/master/petBoss>

example: (C, S) means rewriting using C and S variables.

$$\begin{aligned}
& Sig_{out} = 2C + S \\
1. (S, C) &:= 2(C_1 + g_2 - C_1 g_2) + (1 - (p_2 + g_2 - p_2 g_2)) \\
&= 2C_1 + g_2 - 2C_1 g_2 - p_2 + p_2 g_2 + 1 \\
2. (p_2, g_2) &:= 2C_1 + S_1 c_0 - 2S_1 C_1 c_0 - (1 - (S_1 + c_0 - S_1 c_0)) + (1 - (S_1 + c_0 - S_1 c_0)) S_1 c_0 + 1 \\
&= 2C_1 + \mathbf{S_1 c_0} - 2S_1 C_1 c_0 + S_1 + c_0 - \mathbf{S_1 c_0} + \mathbf{S_1 c_0} - \mathbf{S_1^2 c_0} - \mathbf{S_1 c_0^2} + \mathbf{S_1^2 c_0^2} \\
&= 2C_1 - 2S_1 C_1 + S_1 + c_0 \\
3. (S_1, C_1) &:= 2(1 - g_1) - 2(1 - g_1)(p_1 g_1) c_0 + p_1 g_1 + c_0 \\
&= 2 - 2g_1 - 2(\mathbf{p_1 g_1} - \mathbf{p_1 g_1^2}) + p_1 g_1 + c_0 \\
&= 2 - 2g_1 + p_1 g_1 + c_0 \\
4. (p_1, g_1) &:= 2 - 2(1 - ab) + (a + b - ab)(1 - ab) + c_0 \\
&= \mathbf{2ab} + a + b - ab - \mathbf{a^2 b} - \mathbf{ab^2} + \mathbf{a^2 b^2} = a + b + c_0
\end{aligned} \tag{1}$$

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